

FEM

1. For a 2D body, the stresses, strains with initial strain are related as :- $\sigma = D(\epsilon - \epsilon_0)$
2. From the theory of mechanics of solids, for plane stress conditions the initial strain, ϵ_0 can be written as :-
>
3. What is the size of the element body force vector, f^e of a 2D element? :-> 6X1
4. Which of the following represents the 2D element Stiffness matrix K^e :-> $t_e A_e B^T D B$
5. In a 2D element, what is the size of the element strain displacement matrix ? :-> 3X6
6. From the knowledge of area of triangle, what is the value of $\det J$ in terms of area of the triangle? :-
> twice the area of the triangle
7. For a 2D element, what is $\det J$ when J is denoted as the Jacobian of the transformation? :-
>
8. What is the Jacobian matrix size of a basic linear 2D element? :-> 2X2
9. In a 2D element, $N_2=0.25$, $N_3=0.3$ what is the value of N_1 :-> 0.45
10. In a 2D element, $N_1=0.3$, $N_2=0.2$ what is the value of N_3 :-> 0.5
11. What is the size of the shape function matrix N , of a 2D element? :-> 2X6
12. In a 2D element, the shape functions can be physically represented by area coordinates. A point in a triangle divides it into three areas, . The shape N_1 is represented as :-> A_1/A
13. In a 2D element, what is the value of summation of all the shape functions at every point inside the triangle? :-> 1
14. In a 2D element, the value of shape function N_2 at node 1 is :-> zero
15. In a 2D element, the value of shape function N_1 at node 1 is :-> 1
16. The number of shape functions in a 2D element is :-> 3
17. In a 2D problem, for the constant strain triangle, the shape functions varies over the element as :-
> Linear
18. The element displacement vector for a 2D element is :-> $q = [q_1, q_2, q_3, q_4, q_5, q_6]^T$
19. The number of nodes present in a basic 2D linear element is :-> 3
20. In a 2D problem, what is the degree of freedom of each node? :-> 2
21. In a 2D problem, the basic 2D element is :-> triangle
22. In a 2D problem, the stress-strain relationship is represented as :-> $\sigma = D \epsilon$
23. In a 2D problem, the shear strain in XY direction is given as :-> $(du/dy + dv/dx)$
24. In a 2D body, the elemental volume (dv) is given as :-> tdA
25. In a 2D problem, the strain and its components are given as :-> $\epsilon = \begin{bmatrix} \epsilon_{xx} & \epsilon_{xy} \\ \epsilon_{xy} & \epsilon_{yy} \end{bmatrix}$
26. In a 2D problem, the stress and its components are given as :-> $\sigma = \begin{bmatrix} \sigma_{xx} & \sigma_{xy} \\ \sigma_{xy} & \sigma_{yy} \end{bmatrix}$
27. In a 2D problem, the displacement vector is given as :-> $u = [u, v]^T$
28. What is the size of the element stiffness matrix K_e of a beam element? :-> 4X4
29. The total number of shape functions in a hermite shape function are :-> 4
30. In a beam element, the hermite shape function is represented by an expression of order :-> cubic order
31. In a beam element, the element displacement vector is :-> $q = [q_1, q_2, q_3, q_4]^T$
32. In a beam element, what is the degree of freedom of each node? :-> 2
33. As per the elementary beam theory, the relationship between σ , M and I is :-> $\sigma \times I = -M.y$
34. What do you mean by a Beam :-> Slender member used for supporting transverse loading
35. In a quadratic element, what is the size of element body force vector, f^e :-> 3 x 1
36. In a quadratic element, what is the size of element Traction force vector, T_e :-> 3 x 1
37. In a quadratic element, what is the size of element stiffness matrix, K :-> 3 x 3
38. In a quadratic element, what is the size of element displacement vector, q :-> 3 x 1
39. In a quadratic element, what is the size of shape function matrix, N :-> 1 x 3
40. In a quadratic element, the quadratic shape function N_3 is denoted as :-> $(1+\xi)(1-\xi)$
41. In a quadratic element, the quadratic shape function N_2 is denoted as :->

42. In a quadratic element, the quadratic shape function 'N1' is denoted as :- $\frac{1}{2}(1-\xi)$
43. In a quadratic element, what is the value of ξ at node 3 :- 0
44. In a quadratic element, what is the value of ξ at node 2 :- 1
45. In a quadratic element, what is the value of ξ at node 1 :- -1
46. In a quadratic element, what is the element displacement vector 'q' :- $q = [q_1, q_2, q_3]^T$
47. In a quadratic element what is the internal node :- 3
48. What is the value of deformation at fixed end of a cantilever beam when it is subjected to point load at free end. :- ZERO
49. For linear one dimensional problem, what is the size of the global stiffness matrix when 'N' denotes the number nodes? :- $N \times N$
50. In a 1D problem, what is the value of integral of a shape function :- 1
51. In a 1D problem, the element traction force vector, T_e , is given as :-
52. In a 1D problem, the element body force vector, f_e , is denoted as :-
53. In a 1D problem, what is the size of the element stiffness matrix, K :- 2×2
54. In a 1D problem, what is the relationship between ϵ , B and q :- $\epsilon = Bq$
55. In a 1D problem, what is the size of the element strain-displacement matrix, B is :- 1×2
56. In a 1D problem, the isoparametric formulation in terms of N_1 and N_2 as :- $x = \xi$
57. In a 1D problem, the element displacement vector q is denoted as :- $q = [q_1, q_2]^T$
58. In a 1D problem, the shape function matrix 'N' is denoted as :- $N = \begin{bmatrix} 1-\xi & \xi \end{bmatrix}$
59. In a 1D problem, the linear displacement field within the element can be written in terms of the nodal displacements q_1 and q_2 in matrix notation as :- $u = Nq$
60. In a 1D problem, the linear displacement field within the element can be written in terms of the nodal displacements q_1 and q_2 as :- $u = \begin{bmatrix} 1-\xi & \xi \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix}$
61. In a 1D problem, the linear shape function N_2 is denoted as :- $(1+\xi)/2$
62. In a 1D problem, the linear shape function N_1 is denoted as :- $(1-\xi)/2$
63. In a 1D problem, the length of an element is covered when natural coordinate, ξ changes from :- -1 to 1
64. What do you mean by element connectivity in a finite element modeling? :- It establishes local-global correspondence
65. In a 1D problem stepped bar with 4 steps is discretized into 4 linear elements then what are the number of nodes present in the problem :- 5
66. In a 1D problem, stepped bar with 3 steps is discretized into 3 linear elements then what are the number of nodes present in the problem :- 4
67. In a 1D problem, stepped bar with 2 steps is discretized into 2 linear elements then what are the number of nodes present in the problem :- 3
68. In a 1D problem, what is the degree of freedom (dof) of each node :- 1
69. For 1D problems, the differential volume dv can be written as :- $A dx$
70. What is the nature of stress-strain curve of a cast iron material? :- a straight line
71. For linear elastic materials, the strain energy per unit volume in the body is :- $\frac{1}{2} \epsilon^T \sigma$
72. Under plane strain condition the strain by its components is represented as :- $\epsilon = \begin{bmatrix} \epsilon_x & \epsilon_y & \epsilon_{xy} \end{bmatrix}$
73. Under plane stress condition the stress by its components is represented as :- $\sigma = \begin{bmatrix} \sigma_x & \sigma_y & \tau_{xy} \end{bmatrix}$
74. The surface traction acting on a 3D body is represented by its components as :- $T = [T_x, T_y, T_z]^T$
75. Distributed force acting on a 3D body is represented as :- $f = [f_x, f_y, f_z]^T$
76. A load 'p' acting at a point 'i' is represented by its three components as :- $P_i = [P_{ix}, P_{iy}, P_{iz}]^T$
77. What is the size of material matrix of a 2D body? :- 3×3
78. What is the size of material matrix of a 3D body? :- 6×6
79. What is the engineering shear strain of a 3D body in YZ direction? :- $dv/dz + dw/dy$
80. What is the engineering shear strain of a 3D body in XZ direction? :- $du/dz + dw/dx$
81. What is the engineering shear strain of a 3D body in XY direction? :- $du/dy + dv/dx$
82. How 2D problems are modeled :- Modeled as plane stress and plane strain
83. What is a shear strain? :- Ratio of shear stress and shear modulus
84. What are the units for the coefficient of linear expansion? :- per deg C
85. Which one of the following refers to the isotropic materials? :- Material properties are constant in all directions
86. How do you define a stress? :- Force per unit area
87. What is the traction force of a 1D body? :- force per unit length
88. What is the traction force of a 2D body? :- Force per unit area
89. What is the Body Force? :- force per unit volume
90. In a plane strain condition :- Strains in Z-direction are zero

91. If a thin planar body is said to be in plane stress condition :-> stresses in Z-direction are zero
92. What is the Poisson's ratio? :-> The ratio of lateral strain to longitudinal strain
93. What is the potential energy of an elastic body? :-> Strain energy + work potential
94. When do you say that a problem is plane-strain problem? :-> If a long body of uniform cross section is subjected to transverse loading along its length.
95. When do you say that a problem is plane-stress problem? :-> If a thin planar body subjected to in-plane loading on its edge surface.
96. In a 1D body what is the relationship between stress and strain :-> $\sigma = E \epsilon$
97. In a 2D body what is the relationship between stress and strain :-> $\sigma = E \epsilon$
98. In a 3D body what is the relationship between stress and strain :-> $\sigma = E \epsilon$
99. What is the relationship between modulus of rigidity and modulus of elasticity in terms of Poisson's ratio? :-> $E = 2G(1 + \nu)$
100. In a 3D body what is the strain-displacement relationship in Z-direction? :-> $\epsilon_z = dw/dz$
101. In a 3D body what is the strain-displacement relationship in Y-direction? :-> $\epsilon_y = dv/dy$
102. In a 3D body what is the strain-displacement relationship in X-direction? :-> $\epsilon_x = du/dx$
103. What are the three shear stresses in a 3D element? :-> $\tau_{xy}, \tau_{yz}, \tau_{zx}$
104. In a 3D body what are the three normal stresses along the coordinate axis? :-> $\sigma_x, \sigma_y, \sigma_z$